NOTES:

1. The first and last sheets of this manual are the front and back covers.

2. Front and back covers to be 10 point weight, coated one side (lettering side)(10. C1S), all other sheets to be 20 lb bond.

3. All lettering and graphics to be black, except as follows: The Sypris logos on front and back covers to be red PMS 200, except for the word “SYPRIS” which is to be blue PMS 286. The F.W. Bell logos on the front and back covers to be blue PMS 286, except for “F.W. BELL” which is to be black.

4. Marking Criteria:
   
   A. Each letter, number or image is complete: No lines forming a character are missing or broken.

   B. Lines are sharply defined and uniform in width.

   C. Ink spots forming images are uniform: No thin spots or excessive buildups are present.

   D. Open areas within characters or images are not filled: A, B, 6, 8 etc.

   E. Ink is confined to the lines of the characters: No smeared characters or double images are present.

5. Manuals to be true copies of artwork or electronic file supplied by Sypris Test & Measurement.

6. First article sample required with any new order.

UN-01-230 Rev. E ECO 13096
THIS SIDE BLANK!

(Inside of front cover)
This symbol appears on the instrument and probe. It refers the operator to additional information contained in this instruction manual, also identified by the same symbol.

NOTICE:

See Pages 3-1 and 3-2 for SAFETY instructions prior to first use!
Table of Contents

SECTION-1 INTRODUCTION
Understanding Flux Density.............................................. 1-1
Measurement of Flux Density............................................ 1-2
Product Description........................................................... 1-5
Applications....................................................................... 1-6

SECTION-2 SPECIFICATIONS
Instrument......................................................................... 2-1
Standard Transverse Probe.............................................. 2-3
Standard Axial Probe........................................................ 2-4
Optional Probe Extension Cable....................................... 2-5
Zero Flux Chamber............................................................ 2-6

SECTION-3 OPERATING INSTRUCTIONS
Operator Safety................................................................. 3-1
Operating Features........................................................... 3-3
Instrument Preparation...................................................... 3-5
Power-Up.......................................................................... 3-7
Power-Up Settings............................................................ 3-8
Low Battery Condition....................................................... 3-9
Overrange Condition........................................................ 3-10
AC or DC Measurement Selection..................................... 3-11
UNITS of Measurement Selection..................................... 3-12
RANGE Selection.............................................................. 3-13
HOLD Mode Selection....................................................... 3-15
MIN / MAX Hold Usage.................................................... 3-16
ZERO Function.................................................................. 3-17
Automatic ZERO Function................................................. 3-18
Manual ZERO Function..................................................... 3-20
Sources of Measurement Errors........................................ 3-22
More details on AC Mode Operation................................. 3-25
More details on DC Mode Operation.................................. 3-26
WARRANTY........................................................................ 4-1
### List of Illustrations

<table>
<thead>
<tr>
<th>Figure</th>
<th>Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Figure 1-1</td>
<td>Flux Lines of a Permanent Magnet</td>
<td>1-1</td>
</tr>
<tr>
<td>Figure 1-2</td>
<td>Hall Generator</td>
<td>1-3</td>
</tr>
<tr>
<td>Figure 1-3</td>
<td>Hall Probe Configurations</td>
<td>1-4</td>
</tr>
<tr>
<td>Figure 2-1</td>
<td>Standard Transverse Probe</td>
<td>2-3</td>
</tr>
<tr>
<td>Figure 2-2</td>
<td>Standard Axial Probe</td>
<td>2-4</td>
</tr>
<tr>
<td>Figure 2-3</td>
<td>Optional Probe Extension Cable</td>
<td>2-5</td>
</tr>
<tr>
<td>Figure 2-4</td>
<td>Zero Flux Chamber</td>
<td>2-6</td>
</tr>
<tr>
<td>Figure 3-1</td>
<td>Auxiliary Power Connector Warnings</td>
<td>3-1</td>
</tr>
<tr>
<td>Figure 3-2</td>
<td>Probe Electrical Warning</td>
<td>3-2</td>
</tr>
<tr>
<td>Figure 3-3</td>
<td>Operating Features</td>
<td>3-3</td>
</tr>
<tr>
<td>Figure 3-4</td>
<td>Battery Installation</td>
<td>3-5</td>
</tr>
<tr>
<td>Figure 3-5</td>
<td>Probe Connection</td>
<td>3-6</td>
</tr>
<tr>
<td>Figure 3-6</td>
<td>Power-Up Display</td>
<td>3-7</td>
</tr>
<tr>
<td>Figure 3-7</td>
<td>Missing Probe Indication</td>
<td>3-8</td>
</tr>
<tr>
<td>Figure 3-8</td>
<td>Low Battery Indication</td>
<td>3-10</td>
</tr>
<tr>
<td>Figure 3-9</td>
<td>Overrange Indication</td>
<td>3-10</td>
</tr>
<tr>
<td>Figure 3-10</td>
<td>MODE (AC-DC) Function</td>
<td>3-11</td>
</tr>
<tr>
<td>Figure 3-11</td>
<td>UNITS Function</td>
<td>3-12</td>
</tr>
<tr>
<td>Figure 3-12</td>
<td>RANGE Function</td>
<td>3-14</td>
</tr>
<tr>
<td>Figure 3-13</td>
<td>HOLD Function</td>
<td>3-16</td>
</tr>
<tr>
<td>Figure 3-14</td>
<td>Automatic ZERO Function</td>
<td>3-19</td>
</tr>
<tr>
<td>Figure 3-15</td>
<td>Manual ZERO Function</td>
<td>3-21</td>
</tr>
<tr>
<td>Figure 3-16</td>
<td>Probe Output versus Flux Angle</td>
<td>3-23</td>
</tr>
<tr>
<td>Figure 3-17</td>
<td>Probe Output versus Distance</td>
<td>3-23</td>
</tr>
<tr>
<td>Figure 3-18</td>
<td>Flux Density Variations in a Magnet</td>
<td>3-24</td>
</tr>
<tr>
<td>Figure 3-19</td>
<td>Low AC Signal Indication</td>
<td>3-25</td>
</tr>
</tbody>
</table>
UNDERSTANDING FLUX DENSITY

Magnetic fields surrounding permanent magnets or electrical conductors can be visualized as a collection of magnetic flux lines; lines of force existing in the material that is being subjected to a magnetizing influence. Unlike light, which travels away from its source indefinitely, magnetic flux lines must eventually return to the source. Thus all magnetic sources are said to have two poles. Flux lines are said to emanate from the “north” pole and return to the “south” pole, as depicted in Figure 1-1.

![Flux Lines of a Permanent Magnet](image)

One line of flux in the CGS measurement system is called a maxwell (M), but the weber (W), which is $10^8$ lines, is more commonly used.

Flux density, also called magnetic induction, is the number of flux lines passing through a given area. It is commonly assigned the symbol “$B$” in scientific documents. In the CGS system a gauss (G) is one line of flux passing through a 1 cm$^2$ area. The more
commonly used term is the *tesla* (T), which is 10,000 lines per cm$^2$. Thus

\[
1 \text{ tesla} = 10,000 \text{ gauss} \\
1 \text{ gauss} = 0.0001 \text{ tesla}
\]

Magnetic field strength is a measure of force produced by an electric current or a permanent magnet. It is the ability to induce a magnetic field “$B$”. It is commonly assigned the symbol “$H$” in scientific documents. The unit of “$H$” in the CGS system is an *oersted* (Oe), but the *ampere-meter* (Am) is more commonly used. The relationship is

\[
1 \text{ oersted} = 79.6 \text{ ampere-meter} \\
1 \text{ ampere-meter} = 0.01256 \text{ oersted}
\]

It is important to know that magnetic field strength and magnetic flux density are not the same. Magnetic field strength deals with the physical characteristics of magnetic materials whereas flux density does not. The only time the two are considered equal is in free space (air). Only in free space is the following relationship true:

\[
1 \text{ G} = 1 \text{ Oe} = 0.0001 \text{ T} = 79.6 \text{ Am}
\]

**MEASUREMENT OF FLUX DENSITY**

A device commonly used to measure flux density is the *Hall generator*. A Hall generator is a thin slice of a semiconductor material to which four leads are attached at the midpoint of each edge, as shown in Figure 1-2.
INTRODUCTION

A constant current ($I_c$) is forced through the material. In a zero magnetic field there is no voltage difference between the other two edges. When flux lines pass through the material the path of the current bends closer to one edge, creating a voltage difference known as the Hall voltage ($V_h$). In an ideal Hall generator there is a linear relationship between the number of flux lines passing through the material (flux density) and the Hall voltage.

The Hall voltage is also a function of the direction in which the flux lines pass through the material, producing a positive voltage in one direction and a negative voltage in the other. If the same number of flux lines pass through the material in either direction, the net result is zero volts. This sensitivity to flux direction makes it possible to measure both static (dc) and alternating (ac) magnetic fields.

The Hall voltage is also a function of the angle at which the flux lines pass through the material. The greatest Hall voltage occurs when the flux lines pass perpendicularly through the material. Otherwise the output is related to the cosine of the difference between 90° and the actual angle.

The sensitive area of the Hall generator is generally defined as the largest circular area within the actual slice of the material. This
active area can range in size from 0.2 mm (0.008”) to 19 mm (0.75”) in diameter. Often the Hall generator assembly is too fragile to use by itself so it is often mounted in a protective tube and terminated with a flexible cable and a connector. This assembly, known as a Hall probe, is generally provided in two configurations:

In “transverse” probes the Hall generator is mounted in a thin, flat stem whereas in “axial” probes the Hall generator is mounted in a cylindrical stem. The axis of sensitivity is the primary difference, as shown by “B” in Figure 1-3. Generally transverse probes are used to make measurements between two magnetic poles such as those in audio speakers, electric motors and imaging machines. Axial probes are often used to measure the magnetic field along the axis of a coil, solenoid or traveling wave tube. Either probe can be used where there are few physical space limitations, such as in geomagnetic or electromagnetic interference surveys.
INTRODUCTION

Handle the Hall probe with care. Do not bend the stem or apply pressure to the probe tip as damage may result. Use the protective cover when the probe is not in use.

PRODUCT DESCRIPTION

The MODEL 5070 GAUSS / TESLAMETER is a portable instrument that utilizes a Hall probe to measure magnetic flux density in terms of gauss, tesla or ampere-meter. The measurement range is from 0.01 mT (0.1 G or 0.01 kAm) to 1.999T (19.99 kG or 1591 kAm). The instrument is capable of measuring static (dc) magnetic fields and alternating (ac) fields.

The MODEL 5070 consists of a palm-sized meter and various detachable Hall probes. The meter operates on standard 9 volt alkaline batteries or can be operated with an external ac-to-dc power supply. A retractable bail allows the meter to stand upright on a flat surface. A notch in the bail allows the meter to be wall mounted when bench space is at a premium. The large display is visible at considerable distances. The instrument is easily configured using a single rotary selector and two pushbuttons.

Three measurement ranges can be selected or the meter can automatically select the best range based on the present flux density being measured. A “zero” function allows the user to remove undesirable readings from nearby magnetic fields (including earth’s) or false readings caused by initial electrical offsets in the probe and meter. Included is a “zero flux chamber” which allows the probe to be shielded from external magnetic fields during this operation. The “zero” adjustment can be made manually or automatically.
INTRODUCTION

Other features include two “hold” modes, allowing either the arithmetic maximum or minimum values to be held indefinitely until reset by the user.

The meter, probes and accessories are protected when not in use by a sturdy carrying case.

APPLICATIONS

- Sorting or performing incoming inspection on permanent magnets, particularly multi-pole magnets.
- Testing audio speaker magnet assemblies, electric motor armatures and stators, transformer lamination stacks, cut toroidal cores, coils and solenoids.
- Determining the location of stray fields around medical diagnostic equipment.
- Determining sources of electromagnetic interference.
- Locating flaws in welded joints.
- Inspection of ferrous materials.
- 3-dimensional field mapping.
- Inspection of magnetic recording heads.
Section 2
Specifications

<table>
<thead>
<tr>
<th>INSTRUMENT</th>
<th>RANGE</th>
<th>RESOLUTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>GAUSS</td>
<td>TESLA</td>
<td>Am</td>
</tr>
<tr>
<td>200 G</td>
<td>20 mT</td>
<td>16 kAm</td>
</tr>
<tr>
<td>2 kG</td>
<td>200 mT</td>
<td>159 kAm</td>
</tr>
<tr>
<td>20 kG</td>
<td>2 T</td>
<td>1591 kAm</td>
</tr>
</tbody>
</table>

ACCURACY (including probe):

dc mode: ± 2 % of reading, ± 3 counts

ac mode:

20 - 10,000 Hz: ± 3.5 % of reading, ± 5 counts

ACCURACY CHANGE WITH TEMPERATURE
(not including probe): ± 0.02 % / °C typical

WARMUP TIME TO RATED ACCURACY: 15 minutes

MIN / MAX HOLD ACQUISITION TIME:

dc mode: 180 ms typical

ac mode: 300 ms typical

BATTERY TYPE: 9 Vdc alkaline (NEDA 1640A)

BATTERY LIFE: 8 hours typical (two batteries)
SPECIFICATIONS

**AUXILIARY POWER:** 9 Vdc, 300 mA

**AUXILIARY POWER CONNECTOR:** Standard 2.5 mm I.D. / 5.5 mm O.D. connector. Center post is positive (+) polarity.

**OPERATING TEMPERATURE:** 0 to +50°C (+32 to +122°F)

**STORAGE TEMPERATURE:** -25 to +70°C (-13 to +158°F)

**METER DIMENSIONS:**
- Length: 13.2 cm (5.2 in)
- Width: 13.5 cm (5.3 in)
- Height: 3.8 cm (1.5 in)

**WEIGHT:**
- Meter w/batteries: 400 g (14 oz.)
- Shipping: 1.59 kg (3 lb., 8 oz.)

**REGULATORY INFORMATION:**

Compliance was demonstrated to the following specifications as listed in the official Journal of the European Communities:

**EN 50082-1:1992**
- Generic Immunity
  - IEC 801-2:1991 Electrostatic Discharge Immunity
  - ENV 50140:1993 Radiated Electromagnetic Immunity
  - IEC 1000-4-3:1995 Field Immunity

**EN 50081-1:1992**
- Generic Emissions
  - EN 55011:1991 Radiated and Conducted Emissions
STANDARD TRANSVERSE PROBE

MODEL NUMBER: STH57-0404

FLUX DENSITY RANGE: 0 to ± 2 T (0 to ± 20 kG)

FREQUENCY BANDWIDTH: 0 - 10 kHz

OFFSET CHANGE WITH TEMPERATURE: ± 30 µT (300 mG) / °C typical

ACCURACY CHANGE WITH TEMPERATURE: - 0.05% / °C typical

OPERATING TEMPERATURE RANGE: 0 to +75 °C (+32 to +167 °F)

STORAGE TEMPERATURE RANGE: -25 to +75 °C (-13 to +167 °F)

Figure 2-1
Standard Transverse Probe
SPECIFICATIONS

STANDARD AXIAL PROBE

MODEL NUMBER: SAH57-1904

FLUX DENSITY RANGE: 0 to ± 2 T (0 to ± 20 kG)

FREQUENCY BANDWIDTH: 0 - 10 kHz

OFFSET CHANGE WITH TEMPERATURE: ± 30 µT (300 mG) / °C typical

ACCURACY CHANGE WITH TEMPERATURE: - 0.05% / °C typical

OPERATING TEMPERATURE RANGE: 0 to +75 °C (+32 to +167 ºF)

STORAGE TEMPERATURE RANGE: -25 to +75 °C (-13 to +167 ºF)

Figure 2-2
Standard Axial Probe
OPTIONAL PROBE EXTENSION CABLE

MODEL NUMBER: X5000-0006

OPERATING TEMPERATURE RANGE: 0 to +75 °C (+32 to +167°F)

STORAGE TEMPERATURE RANGE: -25 to +75 °C (-13 to +167°F)

Figure 2-3
Optional Probe Extension Cable
SPECIFICATIONS

ZERO FLUX CHAMBER

MODEL NUMBER: YA-111

CAVITY DIMENSIONS:
Length: 50.8 mm (2")
Diameter: 8.7 mm (0.343")

ATTENUATION: 80 dB to 30 mT (300 G)

PURPOSE: To shield the probe from external magnetic fields during the ZERO operation.

Figure 2-4
Zero Flux Chamber
Section 3
Operating Instructions

OPERATOR SAFETY

⚠️ Do not connect the auxiliary power connector to an ac power source. Do not exceed 15 Vdc regulated or 9 Vdc unregulated. Do not reverse polarity. Use only a regulated ac-to-dc power supply certified for country of use.

Figure 3-1
Auxiliary Power Connector Warnings
Do not allow the probe to come in contact with any voltage source greater than 30 Vrms or 60 Vdc.

Figure 3-2
Probe Electrical Warning

Batteries contain ferrous materials that are attracted to magnetic fields. Be careful when operating the instrument near large magnetic fields, as it may move without warning. Extension cables are available to increase the probe cable length, so that the instrument can remain in a safe position with respect to the field being measured with the probe.
OPERATING FEATURES

Figure 3-3
Operating Features

1. **Display.** Liquid crystal display (LCD).

2. **Manual ZERO Control.** In the ZERO mode of operation the user can manually adjust the zero point using this control.

3. **Function Selector.** This control allows the operator to change the meter’s range, units of measure, ac or dc measurement and hold modes. It also engages the ZERO and MEASURE modes of operation.

4. **Battery Compartment Cover.** This cover slides open to allow one or two 9 volt batteries to be installed.

5. **Power Switch.** Push-on / push-off type switch to apply power to the meter.

6. **SELECT Switch.** Momentary pushbutton used in conjunction with the Function Selector 3 to configure
the meter’s range, units of measure, ac or dc measurement and hold modes.

7 **AUTO/HOLD RESET Switch.** Momentary pushbutton used to reset the held reading when one of the HOLD modes is being used, or to start an automatic ZERO operation when in the ZERO mode.

8 **Auxiliary Power Connector.** This is an industry standard 2.5 mm I.D. / 5.5 mm O.D. dc power connector. The meter will accept a regulated dc voltage in the range of 6 - 15 Vdc at 300 mA minimum current or unregulated 9 Vdc. The center pin is positive (+). The internal batteries are disconnected when using this connector.

⚠️ *Do not connect the auxiliary power connector to an ac power source. Do not exceed 15 Vdc regulated or 9 Vdc unregulated. Do not reverse polarity. Use only a regulated ac-to-dc power supply certified for country of use.*

9 **Probe Connector.** The Hall probe or probe extension cable plugs into this connector and locks in place. To disconnect, pull on the body of the plug, *not the cable* !

10 **Meter Stand.** Retractable stand that allows the meter to stand upright when placed on a flat surface. A notch in the stand allows the meter to be mounted to a vertical surface.
INSTRUMENT PREPARATION

1) With the power switch turned off (POWER pushbutton in the full up position) apply pressure to the battery compartment cover at the two points shown in Figure 3-4. Slide the cover open and remove.

2) Install one or two 9 volt alkaline batteries (two batteries will provide longer operating life). The battery compartment is designed so that the battery polarity cannot be reversed. Reinstall the battery compartment cover.

Figure 3-4
Battery Installation
OPERATING INSTRUCTIONS

3) If using an ac-to-dc power supply review Figure 3-1 for safety notes and the SPECIFICATIONS section for voltage and current ratings. When using a power supply the batteries are automatically disconnected.

4) Install the probe or probe extension cable by matching the key way in the connector to that in the mating socket in the meter. The connector will lock in place. To disconnect, pull on the body of the plug, *not the cable!*

![Probe Connection](image)

Figure 3-5
Probes Connection
POWER-UP

Depress the POWER switch. There will be a momentary audible beep and all display segments will appear on the display.

The instrument will conduct a self test before measurements begin. If a problem is detected the phrase “Err” will appear on the display followed by a 3-digit code. The circuitry that failed will be retested and the error code will appear after each failure. This process will continue indefinitely or until the circuitry passes the test. A condition in which a circuit fails and then passes should not be ignored because it indicates an intermittent problem that should be corrected.

If the self test is successful the meter will perform a self calibration. During this phase the meter will display the software revision number, such as “r 1.0”. Calibration will halt if there is no Hall probe connected. Until the probe is connected the phrase “Err” will appear accompanied by a flashing “PROBE” annunciator as shown in Figure 3-7.

Figure 3-6
Power-Up Display
After power-up the position of the FUNCTION selector switch will determine what happens next. For instance if the selector is in the RANGE position the meter will wait for the user to change the present range. If in the MEASURE position flux density measurements will begin.

Allow adequate time for the meter and probe to reach a stable temperature. See the SPECIFICATIONS section for specific information.

POWER-UP SETTINGS

The meter permanently saves certain aspects of the instrument’s setup and restores them the next time the meter is turned on. The conditions that are saved are:

- RANGE setting (including AUTO range)
- MODE (ac or dc)
- UNITS of measure (gauss, tesla or ampere-meter)
- HOLD mode (min or max)
Other aspects are not saved and default to these conditions:

ZERO mode (inactive)

**NOTE:** The present setup of the instrument is saved only when the FUNCTION selector is returned to the MEASURE position. For example assume the meter is in the MEASURE mode on the 20 mT range. The FUNCTION selector is now turned to the RANGE position and the 200 mT range is selected. The meter is turned off and on again. The meter will be restored to the 20 mT range because the FUNCTION selector was never returned to the MEASURE mode prior to turning it off.

**LOW BATTERY CONDITION**

The meter is designed to use one or two standard 9V alkaline batteries (two batteries will provide longer operating life). When the battery voltage becomes too low the battery symbol on the display will flash, as shown in Figure 3-8. Replace the batteries or use an external ac-to-dc power supply.

⚠️ **Instrument specifications are not guaranteed when a low battery condition exists!**
OVERRANGE CONDITION

If the magnitude of the magnetic flux density exceeds the limit of the selected range the meter will display a flashing value of “1999” (gauss or tesla mode) or “1591” (ampere-meter mode). The next highest range should be selected. If already on the highest range then the flux density is too great to be measured with this instrument.
AC OR DC MEASUREMENT SELECTION

The meter is capable of measuring either static (dc) or alternating (ac) magnetic fields. To choose the desired mode rotate the function selector to the MODE setting, then press the SELECT pushbutton to select AC or DC on the display.

The dc and ac modes is discussed in more detail later in this section.

This setting is saved and will be restored the next time the meter is turned on.
UNITS OF MEASUREMENT SELECTION

The meter is capable of providing flux density measurements in terms of gauss (G), tesla (T) or ampere-meters (Am). To choose the desired units, rotate the function selector to the UNITS position. Press the SELECT pushbutton to select G, T or Am on the display.

This setting is saved and will be restored the next time the meter is turned on.

Figure 3-11
UNITS Function
RANGE SELECTION

The meter is capable of providing flux density measurements on one of three fixed ranges, or it can be programmed to automatically select the best range for the present flux density. The available ranges are listed in the SPECIFICATIONS section of this manual. The ranges advance in decade steps. The lowest range offers the best resolution while the highest range allows higher flux levels to be measured.

In the AUTO range mode the range is advanced if the reading reaches the full scale of the present range. This is 1999 if in the gauss or tesla mode (such as 199.9 G or 199.9 mT), or 1591 if in the ampere-meter mode (such as 15.91 kAm). The range is lowered if the present reading falls below 10% of full scale for the present range. The speed at which the readings are updated decreases slightly when AUTO ranging is used.

To choose the desired range rotate the function selector to the RANGE position. The “RANGE” legend will flash. Press the SELECT pushbutton to select the desired range or AUTO RANGE on the display.

This setting is saved and will be restored the next time the meter is turned on.
Figure 3-12
RANGE Function
HOLD MODE SELECTION

In some applications it may be desirable to hold a reading that is either greater than or less than all previous readings.

The MAX HOLD function holds the reading that is arithmetically greater than all previous readings. For instance a reading of +125.0 is greater than +99.0 or -150.0.

The MIN HOLD function holds the reading that is arithmetically less than all previous readings. For instance a reading of -125.0 is less than -99.0 or +150.0.

To choose the desired hold mode rotate the function selector to the HOLD position. Press the SELECT pushbutton to select the desired mode on the display. MAX HOLD is indicated by “MX”. MIN HOLD is indicated by “MN”. The “OFF” legend will appear when all HOLD modes are turned off.

This setting is saved and will be restored the next time the meter is turned on.
MIN / MAX HOLD USAGE

See the SPECIFICATIONS section for response time information.

The MAX HOLD function holds the reading that is arithmetically greater than all previous readings. The MIN HOLD function holds the reading that is arithmetically less than all previous readings. These modes are useful in determining the maximum or minimum value of magnetic events that occur over a period of time.

The MIN or MAX HOLD operation begins when the function selector is returned to the MEASURE position. If the reading
exceeds the range limit the meter will hold a flashing value of "1999" (gauss or tesla mode) or "1591" (ampere-meter mode).

The held value can be reset by pressing the HOLD RESET pushbutton. The next value displayed after a reset will be the present value of flux density. For instance if the held reading is 150.0 G and the present flux density is -100.0 G, the meter will display -100.0 G after the reset.

ZERO FUNCTION

“Zeroing” the probe and meter is one of the most important steps to obtaining accurate dc flux density measurements. The ideal Hall generator produces zero output in the absence of a magnetic field, but actual devices are subject to variations in materials, construction and temperature. Therefore most Hall generators produce some output even in a zero field. This will be interpreted by the meter as a flux density signal.

Also, the circuits within the meter can produce a signal even when there is no signal present at the input. This will be interpreted as a flux density signal. Lastly magnetic sources close to the actual field being measured, such as those from electric motors, permanent magnets and the earth (roughly 0.5 gauss or 50 μT), can induce errors in the final reading.

It is vital to remove these sources of error prior to making actual measurements. The process of “zeroing” removes all of these errors in one operation. The meter cancels the combined dc error signal by introducing another signal of equal magnitude with opposite polarity. After zeroing the only dc signal that remains is that produced by the probe when exposed to magnetic flux.
NOTE: Zeroing the meter and probe affects only the static (dc) component of the flux density signal.

There may be situations when the user prefers to shield the probe from all external magnetic fields prior to zeroing. Provided with the meter is a ZERO FLUX CHAMBER which is capable of shielding against fields as high as 30 mT (300 G or 23.88 kAm). The probe is simply inserted into the chamber before the zeroing process begins.

Handle the Hall probe with care. Do not bend the stem or apply pressure to the probe tip as damage may result.

In other situations the user may want the probe to be exposed to a specific magnetic field during the zeroing process so that all future readings do not include that reading (such as the earth’s field). This is possible with the following restrictions:

1) The external field must not exceed 30 mT (300 G or 23.88 kAm).

2) The field must be stable during the zeroing process. It should not contain alternating (ac) components.

AUTOMATIC ZERO FUNCTION

The meter provides two methods to zero the probe. The first is completely automatic. Prepare the probe for zeroing, then rotate the function selector to the ZERO position. The “ZERO” legend will flash and actual dc flux density readings will appear on the display. The meter will select the lowest range regardless of which range was in use prior to using the ZERO function. Recall that the maximum flux density level that can be zeroed is 30 mT (300
G or 23.88 kAm). The meter will switch over to the dc mode of operation during zeroing. Recall that the zeroing operation affects dc errors only.

Press the AUTO pushbutton and the process will begin. The “AUTO” legend will also flash. Once automatic zeroing begins it must be allowed to complete. During this time all controls are disabled except for the POWER switch. The process normally takes from 5 to 15 seconds.
OPERATING INSTRUCTIONS

The meter selects the lowest range and adjusts the nulling signal until the net result reaches zero. If the existing field is too large or unstable the meter will sound a double beep and the phrase “OVER” will appear momentarily on the display. At this point the automatic process is terminated and the flashing “AUTO” legend will disappear. The “ZERO” legend will continue to flash to remind the user that the ZERO mode is still active.

If the nulling process is successful, the next highest range is selected. No further electronic adjustments are made, but at this stage a reading is acquired which will be mathematically subtracted from all future readings on this range. This process is then repeated for the highest range. When finished, the meter will sound an audible beep and the flashing “AUTO” legend will disappear. The “ZERO” legend will continue to flash to remind the user that the ZERO mode is still active. At this point the automatic process can be repeated or a manual adjustment can be performed (see “Manual Zeroing”).

The final zero values will remain in effect until the meter and probe are zeroed again, if the probe is disconnected or if the meter is turned off and back on again.

MANUAL ZERO FUNCTION

The second zeroing method is a manual adjustment. This feature also allows the user to set the “zero” point to something other than zero, if desired. Position the probe for zeroing, then rotate the function selector to the ZERO position. The “ZERO” legend will flash and actual dc flux density readings will appear on the display. The meter will select the lowest range regardless of which range was in use prior to selecting the ZERO function. Recall that the maximum flux density level that can be zeroed is 30 mT (300 G or 23.88 kAm). The meter will switch over to the dc mode of
operation during zeroing. Recall that the zeroing operation affects dc errors only.

![Figure 3-15
Manual ZERO Function](image)

By turning the MANUAL control in either direction the reading will be altered. Turning the control clockwise adds to the reading, turning it counterclockwise subtracts from the reading. Turning it slowly results in a fine adjustment, turning it quickly results in a coarse adjustment.

**NOTE:** Making a manual ZERO adjustment not only affects the lowest range but also the higher ranges, though to a lesser extent. For example, assume an automatic ZERO has already been performed, after which all three ranges should read zero. Now a
manual adjustment is made that causes the reading on the lowest range to be non-zero. The reading on the other ranges may also be non-zero depending upon the magnitude of the change. The adjustment has 10 times less effect on the middle range and 100 times less effect on the highest range.

**SOURCES OF MEASUREMENT ERRORS**

When making flux density measurements there are several conditions that can introduce errors:

1) Operating the meter while the LOW BATTERY symbol appears.  
   
   **⚠️ Instrument specifications are not guaranteed when a low battery condition exists!**

2) Failure to zero the error signals from the meter, probe and nearby sources of magnetic interference.

3) Subjecting the probe to physical abuse.

   **⚠️ Handle the Hall probe with care. Do not bend the stem or apply pressure to the probe tip as damage may result. Use the protective cover when the probe is not in use.**

4) One of the most common sources of error is the angular position of the probe with respect to the field being measured. As mentioned in Section-1, a Hall generator is not only sensitive to the number of flux lines passing through it but also the *angle* at which they pass through it. The Hall generator produces the greatest signal when the flux lines are perpendicular to the sensor as shown in Figure 3-16.
The probe is calibrated and specified with flux lines passing perpendicularly through the Hall generator.

5) As shown in Figure 3-17 the greater the distance between the magnetic source and the Hall probe the fewer flux lines will pass through the probe, causing the probe’s output to decrease.

6) Flux density can vary considerably across the pole face of a permanent magnet. This can be caused by internal physical flaws such as hairline cracks or bubbles, or an inconsistent mix of...
materials. Generally the sensitive area of a Hall generator is much smaller than the surface area of the magnet, so the flux density variations are very apparent. Figure 3-18 illustrates this situation.

![Flux Density Variations in a Magnet](image)

Figure 3-18
Flux Density Variations in a Magnet

7) Using more than one extension cable can result in measurement errors. In some cases the meter may report an error. Total cable length between the meter and the probe connector should not exceed 2.1 m (7 ft).

⚠️ The use of more than one extension cable can result in measurement errors and increase susceptibility to radio frequency interference (RFI).

8) The accuracies of the meter and probe are effected by temperature variations. Refer to the SPECIFICATIONS section for specific information.

MORE DETAILS ON AC MODE OPERATION

3-24
It is possible for the flux density signal to contain both a dc component and an ac component. In the ac mode the value displayed is the true rms value of the waveform with its dc component removed. However if the dc component is too high it may force the peak value of the waveform to exceed the electrical limits of the meter, causing the waveform to clip and introducing errors in the final reading. This can also lead to an overrange condition on the display and can lead to erratic behavior if the AUTO range feature is being used.

As stated in the SPECIFICATIONS section the accuracy of the true rms reading is only guaranteed for readings greater than 5% of the full scale range. For example this would be 1mT on the 200 mT range. When the reading falls below 5% of full scale the “AC” legend on the display will flash, as shown in Figure 3-19. This is intended to remind the user that the reading may not be accurate. Select a lower range if possible to regain accuracy.

![Figure 3-19](image.png)

Low AC Signal Indication
MORE DETAILS ON DC MODE OPERATION

It is possible for the flux density signal to contain both a dc component and an ac component. In the dc mode this can lead to instable readings. If the peak value of the ac component reaches the electrical limits of the meter, even though the average dc level is within the limits, an overrange condition may appear on the display. This situation can also lead to erratic behavior if the AUTO range feature is being used.

The presence of an ac signal can be verified by using the ac mode to determine the magnitude of the ac component.
WARRANTY

This instrument is warranted to be free of defects in material and workmanship. Sypris Test & Measurement’s obligation under this warranty is limited to servicing or adjusting any instrument returned to the factory for that purpose, and to replace any defective parts thereof. This warranty covers instruments which, within one year after delivery to the original purchaser, shall be returned with transportation charges prepaid by the original purchaser, and which upon examination shall disclose to Sypris Test & Measurement’s satisfaction to be defective. If it is determined that the defect has been caused by misuse or abnormal conditions of operation, repairs will be billed at cost after submitting an estimate to the purchaser.

Sypris Test & Measurement reserves the right to make changes in design at any time without incurring any obligation to install same on units previously purchased.

THE ABOVE WARRANTY IS EXPRESSLY IN LIEU OF ALL OTHER WARRANTIES EXPRESSED OR IMPLIED AND ALL OTHER OBLIGATIONS AND LIABILITIES ON THE PART OF SYPRIS TEST & MEASUREMENT, AND NO PERSON INCLUDING ANY DISTRIBUTOR, AGENT OR REPRESENTATIVE OF SYPRIS TEST & MEASUREMENT IS AUTHORIZED TO ASSUME FOR SYPRIS TEST & MEASUREMENT ANY LIABILITY ON ITS BEHALF OR ITS NAME, EXCEPT TO REFER THE PURCHASER TO THIS WARRANTY. THE ABOVE EXPRESS WARRANTY IS THE ONLY WARRANTY MADE BY SYPRIS TEST & MEASUREMENT. SYPRIS TEST & MEASUREMENT DOES NOT MAKE AND EXPRESSLY DISCLAIMS ANY OTHER WARRANTIES, EITHER EXPRESSED OR IMPLIED, INCLUDING WITHOUT LIMITING THE FOREGOING, WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OR ARISING BY STATUE OR OTHERWISE IN LAW OR FROM A COURSE OF DEALING OR USAGE OR TRADE. THE EXPRESS WARRANTY STATED ABOVE IS MADE IN LIEU OF ALL LIABILITIES FOR DAMAGES, INCLUDING BUT NOT LIMITED TO CONSEQUENTIAL DAMAGES, LOST PROFITS OR THE LIKE ARISING OUT OF OR IN CONNECTION WITH THE SALE, DELIVERY, USE OR PERFORMANCE OF THE GOODS. IN NO EVENT WILL SYPRIS TEST & MEASUREMENT BE LIABLE FOR SPECIAL, INDIRECT OR CONSEQUENTIAL DAMAGES EVEN IF SYPRIS TEST & MEASUREMENT HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES.

This warranty gives you specific legal rights, and you may also have other rights that vary from state to state.
THIS SHEET BLANK!

(Back of Warranty)